Volume Contents

Volume 4 Number 1

S. R. KIM, D. HAN and Design and implementation of an automatic adjustment system for integrated tube components Z. BIEN R. N. DANBURY Servomechanisms for incremental motion—power dissipation considerations D.-I. KIM, J. W. JEON and S. KIM Software acceleration/deceleration methods for industrial robots and CNC machine tools C. R. ALLEN and K. RATCLIFF A CAD method for programming a flexible manufacturing cell for robot inspection of mechanical parts Y. N. LEE, T. W. KIM and I. H. SUH A look-up table-based self-organizing fuzzy plus linear controller Call for Papers Conference Announcement 93 95 Inauguration Announcement Instructions for the submission of camera-ready copy

Volume 4 Number 2

SPECIAL ISSUE

MECHATRONICS IN SWEDEN

J. WIKANDER	97	Editorial
K. J. ÅSTRÖM, A. CARLSSON and J. KANNIAH	99	A flexible system for adaptive motion control
K. PAHLAVAN and JO. EKLUNDH	113	Mechatronics of active vision
C. DURING	125	Real-time optical measurement of position
R. W. UUSIJÄRVI and M. E. TÖRNGREN	139	Introducing distributed control in mobile machines based on hydraulic actuators
LB. Fredriksson	159	Controller area networks and the protocol CAN for machine control systems
O. DAHL	173	Path constrained robot control—experimental evaluation

- K. HYYPPÅ 199 Design considerations in a laser navigation system for mobile robots M. LIZELL An actuator for semi-active damping system 207 M. HANSON 217 Teaching mechatronics at tertiary level 227 Call for Papers 229 Conference Announcement Instructions for the submission of camera-ready copy Volume 4 Number 3 J. R. HEWIT 231 Editorial R. A. HIRSCHFELD, T. W. LIAO 233 Mechatronics education developments in the United States: the and L. K. KEYS perspective from Louisiana State University R. L. VASQUEZ and R. H. CANNON, JR 247 Experiments in cooperative manipulation from a flexiblymounted platform J. N. REED and R. D. TILLETT 265 Initial experiments in robotic mushroom harvesting
- J. A. MARCHANT and R. D. TILLETT 281 Software and transputer system design for high speed grading of agricultural produce F. FIGUEROA and A. MAHAJAN 295 Generic model of an autonomous sensor C. A. PATERSON, K. J. BURNHAM, A fixed parameter optimal controller design for an active 317 D. J. G. JAMES and R. A. WILLIAMS suspension system—a sensitivity analysis Technical Note L. MONTRET, H. EKEROL and 331 Object tracking at field rate using the Hough transform D. C. HODGSON 339 Report on Meeting 341 Call for Papers
 - I Instructions for the submission of camera-ready copy

Conference Announcements

Volume 4 Number 4

343

E. Swain

349 Turbocharging the submarine diesel engine

C. L. Hwang and C. H. Lan

369 The position control of electrohydraulic servomechanism via a novel variable structure control

F. K. FADUL and R. P. KRAHE 393 A DSP-based power integrated circuit controller/driver board for stepper motors D. HR. STEFANOV 401 Model of a special orthotic manipulator Survey of range vision systems D. INDYK and S. A. VELASTIN 417 451 Announcing Book Reviews 453 **Book Review** Instructions for the submission of camera-ready copy Volume 4 Number 5 DONG-IL KIM and JIN-WON LEE 455 Commutation of permanent magnet A.C. servo motors with incremental encoders via fuzzy reasoning 471 C. M. LIM Implementation and experimental studies of fuzzy PID controllers Distributed control architecture for a sensor-driven dual arm T. J. TARN, A. K. BEJCZY, 481 NING XI and A. K. RAMADORAI T. G. KING and L. G. TAO 503 An incremental real-time pattern tracking algorithm for linescan camera application J. SOMLO and J. PODURAJEV 517 Optimal cruising trajectory planning for robots C. UME and M. TIMMERMAN 539 Integrated hardware and software designs in mechatronics laboratory courses 551 Announcing Book Reviews Instructions for the submission of camera-ready copy Volume 4 Number 6 B. Y. Duan, Y. H. Qi, G. H. Xu and 553 Study on optimization of mechanical and electronic synthesis W. T. WANG for the antenna structural system SHIUH-JER HUANG and 565 A self-tuning adaptive feed-forward control for a retrofit milling CHUEN-CHUNG CHEN machine KOK-MENG LEE, JIANFA PEI and 581 Kinematic analysis of a three-degrees-of-freedom spherical

607

wrist actuator

laboratory scale greenhouse

An expert system to control humidity and temperature of a

R. ROTH

O. S. TÜRKAY

N. SEPEHRI, F. L. K. WAN,
P. D. LAWRENCE and
G. A. M. DUMONT

WOOSOON YIM

635 Cartesian trajectory control of a flexible manipulator using sliding mode

I Instructions for the submission of camera-ready copy

Volume 4 Number 7

N. D. TILLETT, N. VAUGHAN and A. BOWYER	653	An improved flexible pneumatic joint for horticultural robots
O. H. CHAI, Y. S. WONG and A. N. Poo	673	A DDA parabolic interpolator for computer numerical control of machine tools
T. H. LEE, Q. G. WANG and W. K. TAN	693	A framework for robust neural network-based control of non-linear servomechanisms
C. D. WRIGHT and K. CASE	713	Emulation of modular manufacturing machines using CAD modelling
P. M. HAGELIN and J. R. HEWIT	737	Artificial neural networks for locating eyes in facial images
J. TARAMAA, R. LINTULAMPI and V. SEPPÄNEN	753	Automated assembly of machine control software
	771	Conference Announcement
	I	Instructions for the submission of camera-ready copy

Volume 4 Number 8

N. J. C. Strachan	773	Sea trials of a computer vision based fish species sorting and size grading machine
J. Y. HUNG	785	Torque ripple minimization for variable reluctance motors
K. C. KOH and H. S. CHO	799	A path tracking control system for autonomous mobile robots: an experimental investigation
A. PREUMONT	821	An investigation of the kinematic control of a six-legged walking robot
R. IKEURA, M. KIMURA, H. INOOKA and T. KAMIJIMA	831	Motion planning for computer controlled automata

C. ZIELIŃSKI

P. VÄHÄ, T. HEIKKILA, J. RÖNING and J. OKKONEN 843 Reaction based robot control

861 Machine of the future: an intelligent paper roll manipulator

879 Calls for Papers

I Volume Contents and Author Index for Volume 4, 1994

XI Instructions for the submission of camera-ready copy